

Geography 12: Maps and Spatial Reasoning

## Lecture 16: *New Methods and Issues for Heights on Maps*

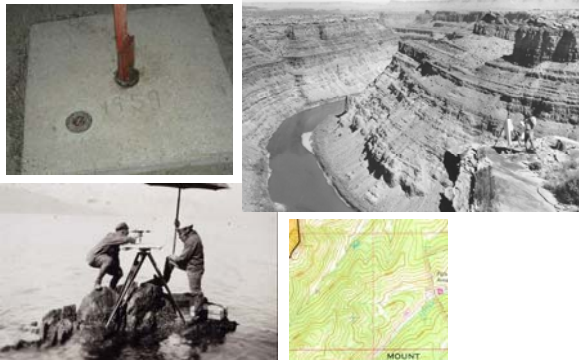
Professor Keith Clarke



### Base line



### Triangulation and Plane Table

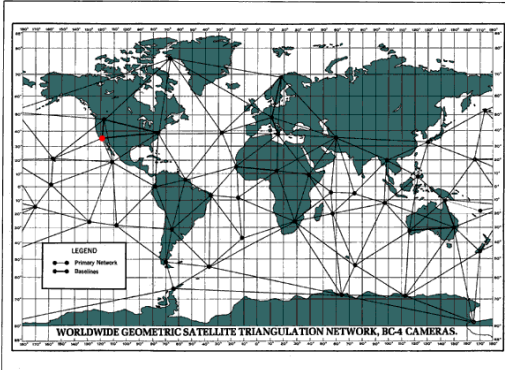


### US Coast and Geodetic Survey:

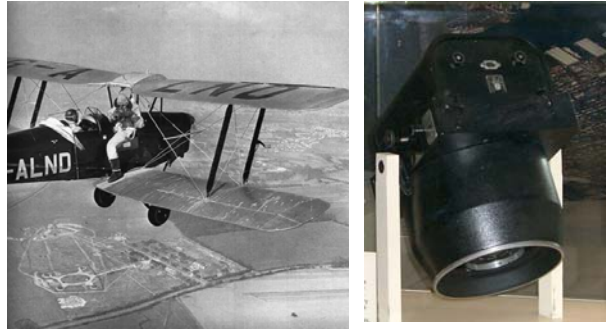
1937 national coverage



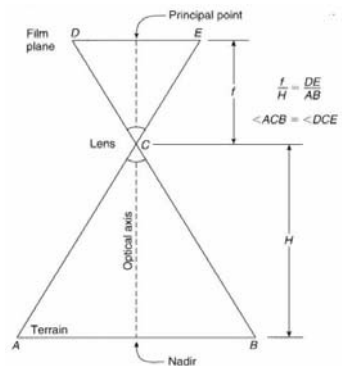
## Triangulations: WGS70



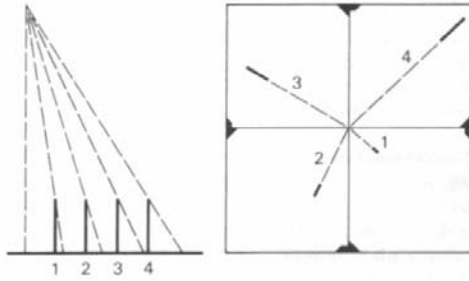
## Post WWII Air photographs



## Principal Point



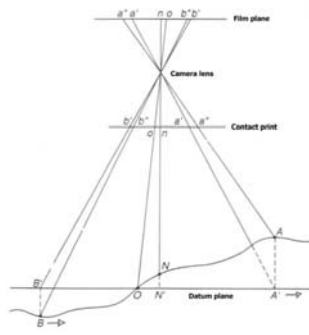
## Radial displacement around nadir



## Relief Displacement

**Relief Displacement**  
 Displacement is the radial distance between where an object appears in an image to where it actually should be according to a planimetric coordinate system. Relief Displacement is caused by changes in the distance between the ground and the camera as the plane flies over the ground. The nadir point is always free of any relief displacement.

Relief Displacement is  
 A) Radially outward for features above the nadir elevation  
 B) Radially inward for features below the nadir elevation



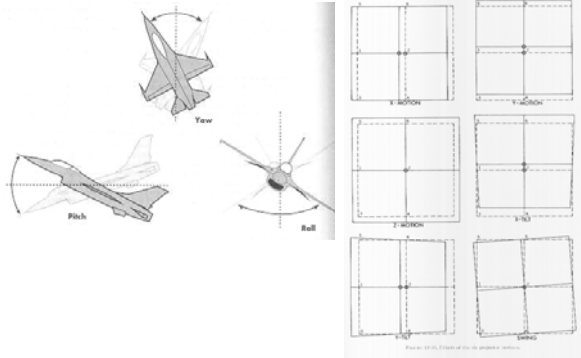
## Height from displacement



Determining height from radial displacement. You can compute the actual height of an object by knowing (1) the radial distance  $r$  from the center of the photograph  $PP$  to the top of the object to be measured, (2) the measured object height  $d$ , and (3) the height of the aircraft  $A$  above the scene.



## Reference axes



## Orthorectification



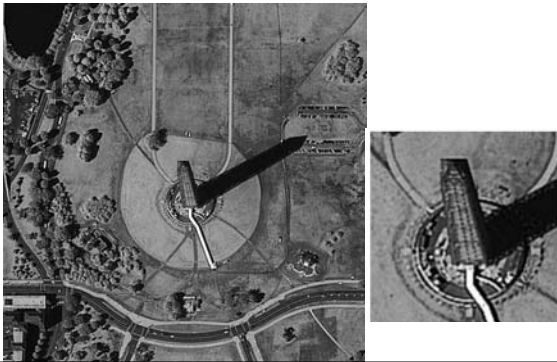
## Ground truth



## Orthorectified



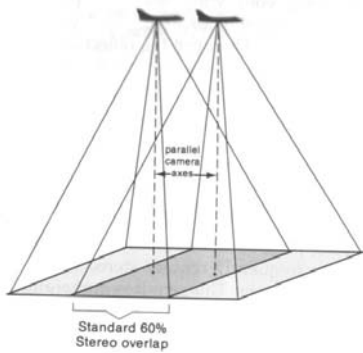
Buildings easy, terrain hard!



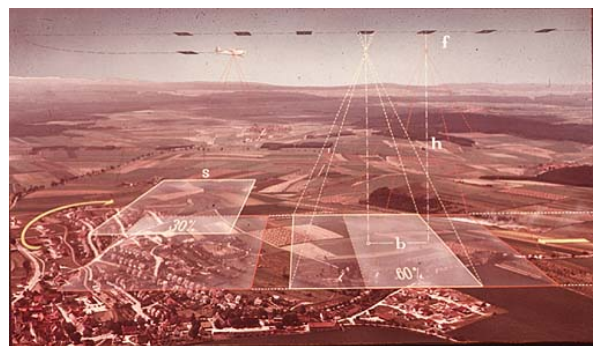
Unless, there are two images



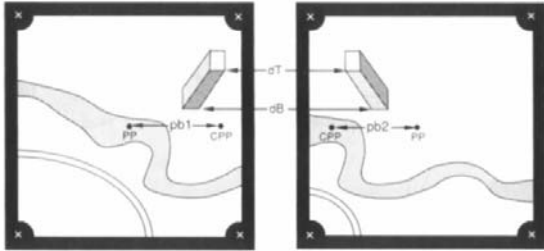
Stereo geometry (Conjugate PP)



Flight line geometry/overlap

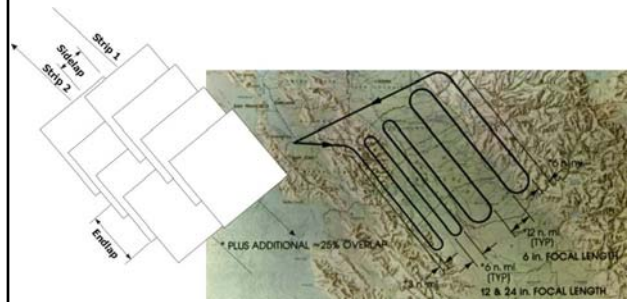


## Height from parallax

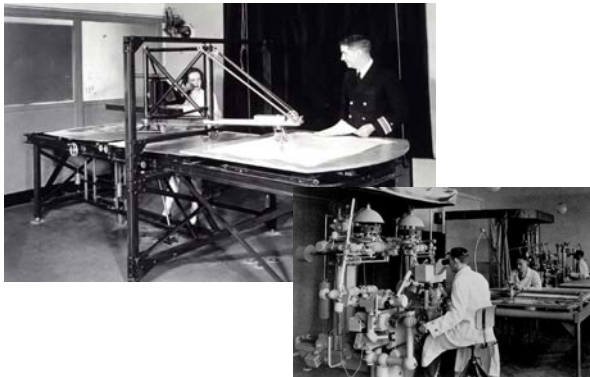


Computing height using differential parallax. The height of an object  $H$  can be determined if you know the differential parallax  $dp$ , absolute or average parallax  $P$ , and the height of the aircraft  $A$  above the scene.

## Flight planning map



## Analog photogrammetry



## Softcopy photogrammetry



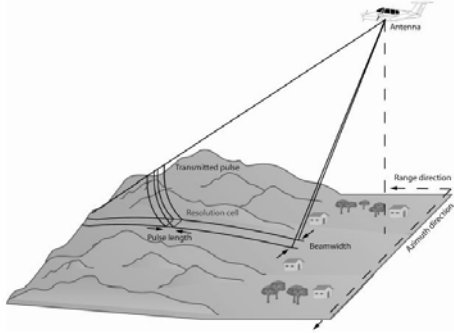
Intergraph Workstations



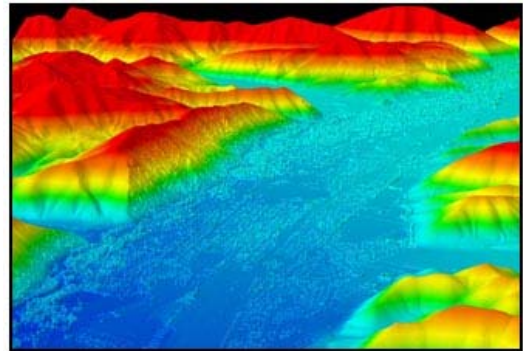
Wild Heerbrug BC2  
Analytical Stereoplotter



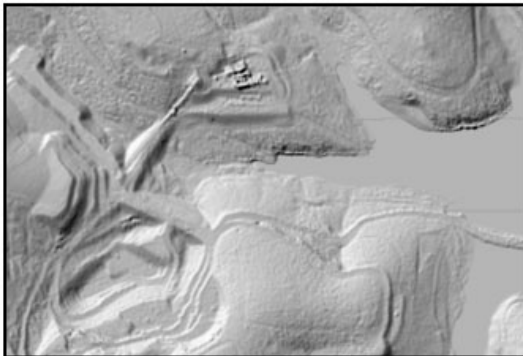
## How SAR works



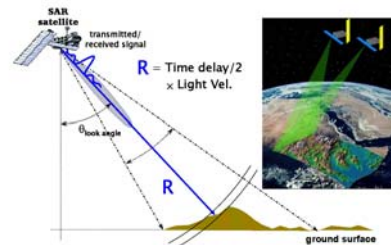
## Terrain Model from IFSAR (Hailey, ID)



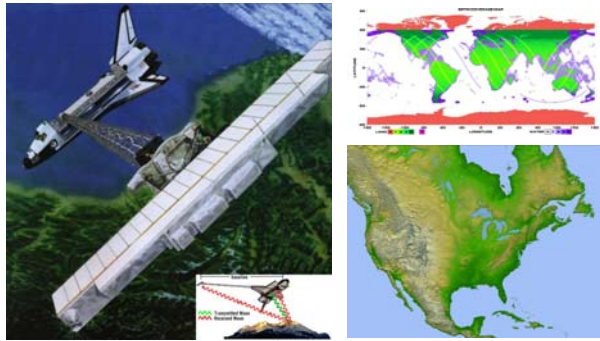
## IFSAR DEM



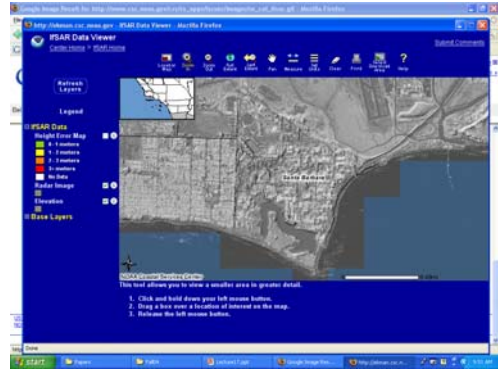
## SAR from Space



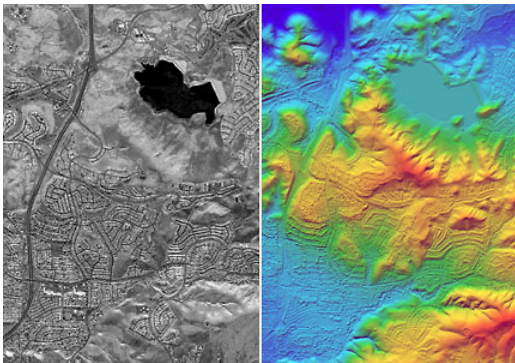
## SRTM: Global topo map



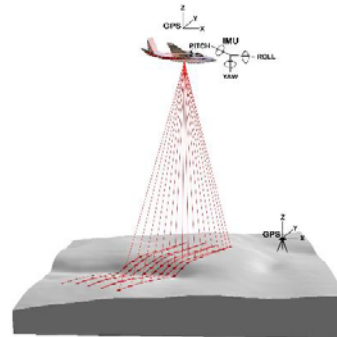
## NOAA Southern Cal. IFSAR viewer



## IFSAR: Thousand Oaks, CA

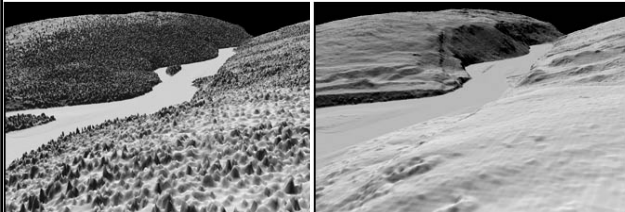


## How Lidar works

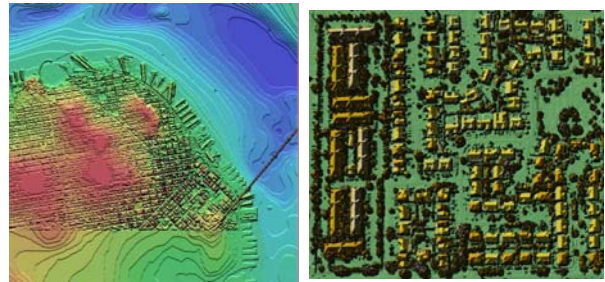




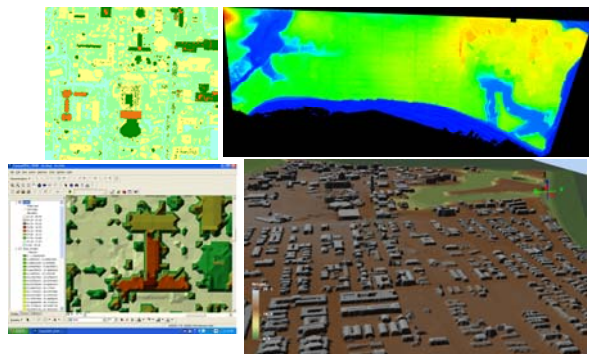
### LIDAR first and last pulse



### LIDAR terrain detail



### 3D Models LiDAR



### LiDAR data

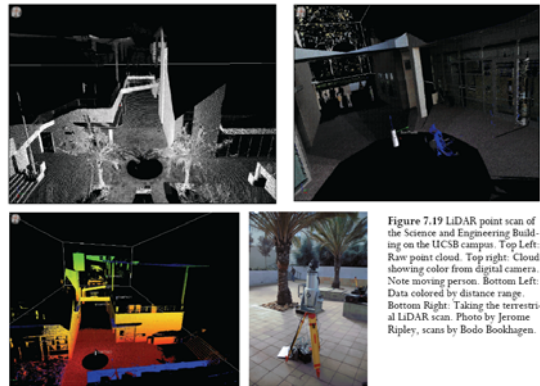
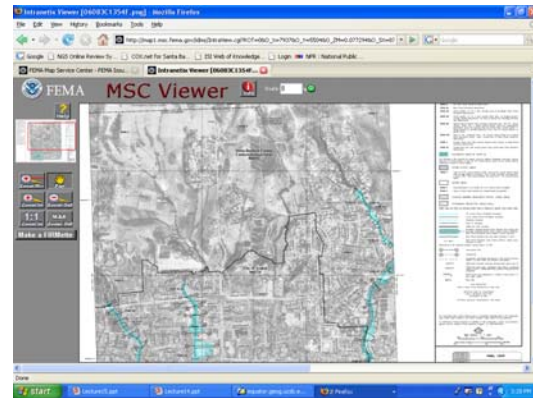


Figure 7.19 LiDAR point scan of the Science and Engineering Building on the UCSB campus. Top Left: Raw point cloud. Top right: Cloud showing color from digital camera. Note moving person. Bottom Left: Data colored by distance range. Bottom Right: Taking the terrestrial LiDAR scan. Photo by Jerome Ripley, scans by Bodo Bookhagen.

## Critical height issue: Floods/Sea Level



## FEMA: D-FIRMs



## Summary

- First generation topographic mapping used triangulation and plane table
- Second generation used stereo photogrammetry
- New generation uses IFSAR and LIDAR
- Unprecedented accuracy
- What surface to map?